



# DEPARTMENT OF SCHOOL EDUCATION TAMIL NADU



STANDARD - 11

**QB365-Question Bank Software** 

State Council of Educational Research and Training
Chennai 600 006

### **QB365-Question Bank Software** SYLLABUS 2020–2021

## SYLLABUS 2020-2021 SUBJECT: MATHEMATICS

#### CLASS: 11

CLASS: 11	CONT	CONTENT	
UNIT	1.1.	Introduction	
1. Sets, Relations and Functions	1.2.	Sets	
	1.2.1.	Properties of Set Operations	
	1.4.	Constants and Variables, Intervals and Neighborhoods	
	1.4.1.	Constants and Variables	
	1.4.2.	. INITIAL PROPERTY	
	1.5.		
	1.5.1.	Type of Relations	
	1.6.	Functions	
	1.6.1.	Ways of Representing Functions	
	1.6.2.	Some Elementary Functions	
	1.6.5.	Inverse of a Function	
	1.6.6.	Algebra of Functions	
	1.6.7.	Some Special Functions	
2. Basic Algebra	2.1.	Introduction	
	2.3.	Absolute Value	
	The state of the s	Definition and Properties	
	2.3.2.	Equations Involving Absolute Value	
		Some Results For Absolute Value	
	2.3.4.	Inequalities Involving Absolute Value	
	2.4.	Linear Inequalities	
		Quadratic Functions	
	2.5.1.	Quadratic Formula	
	2.5.2.	Quadratic Inequalities	
	2.7.	Rational Functions	
	2.7.1.	Rational Inequalities	
	2.1.2.	Partial Fractions	
	2.8.	Exponents and Radicals	
	2.8.1.	Exponents	
	2.8.2.	Radicals	

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	2.8.3.	Exponential Function
	2.9.	Logarithm
	2.9.1.	
	2.10.	Application of Algebra in Real Life
3. Trignometry	3.1.	Introduction
	3.2.	A recall of basic results
	3.2.5.	Co terminal angles
	3.3.	Radian Measure
	3.3.1.	Relationship between Degree and Radian Measures
	3.4.	Trigonometric functions and their properties
	3.4.1.	Trigonometric Functions of any angle in terms of Cartesian coordinates
	3.4.2.	Trigonometric Functions of real numbers
	3.4.3.	Allied Angles
	3.4.4.	Some Characteristics of Trigonometric Functions
	3.5.	Trigonometric Identities
	3.5.1.	Sum and difference identities or compound angles formulas
	3.5.2.	Multiple angle identities and submultiple angle identities
	3.5.3.	Product to Sum and Sum to Product Identities
4. Combinatorics	4.1.	Introduction
and Mathematical	4.2.	Fundamental principles of counting
Induction	4.3.	Factorials
	4.4.	Permutations (Theorem 4.1-4.3 without proof)
	4.4.1.	Permutations of distinct objects
	4.4.2.	Properties of Permutations. (without proof)
	4.4.3.	Objects always together (String method)
	4.4.4.	No two things are together (Gap method)
	4.4.5.	Permutations of not all distinct objects
Control of the second	4.5.	Combinations

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	4.5.1.	Properties of Combinations (without proof)
	4.6.	Mathematical induction
5. Binomial Theorem, Sequences and Series	5.1.	Introduction (Theorem 5.2, 5.3 without proof)
	5.4.	Finite Sequences
	5.4.1.	Arithmetic and Geometric Progressions
	5.5.	Finite Series
	5.5.2.	Telescopic Summation for Finite Series
A STATE OF THE STA	5.6.	Infinite Sequences and Series
	5.6.1.	Fibonacci Sequence
The state of the s	5.6.2.	Infinite Geometric Series
	5.6.4.	Telescopic Summation for Infinite Series
A TANK TO THE SAME OF THE SAME	5.6.5.	Binomial Series
6. Two Dimensional	6.1.	Introduction
Analytical Geometry	6.2.	Locus of a point
	6.3.	Straight Lines
	6.3.1.	The relationship between the angle of inclination and slope
	6.3.2.	Intercepts of a Line
	6.3.3.	Different Forms of an equation of a straight line
	6.3.4.	General form to other forms
	6.4.	Angle between two straight lines
	6.4.1.	Condition for Parallel Lines
	6.4.2.	Condition for perpendicular Lines
and the second second second	6.4.3.	Position of a point with respect to a straight line
	6.4.4.	Distance Formulas
Some deallers.	6.4.5.	Family of lines
	6.4.6.	One parameter families
	6.4.7.	Two parameters families
	6.5.	Pair of Straight Lines
	6.5.1.	Pair of Lines Passing through the Origin
	6.5.2.	Angle between Pair of Straight Lines
	6.5.3.	Equation of the bisectors of the angle between the lines $a\chi^2 + 2h\chi\gamma + b\gamma^2 = 0$
	6.5.4.	General form of Pair of Straight Lines

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7. Matrices and	7.1.	Introduction
Determinants	7.2.	Matrices
	7.2.4.	Properties of Matrix Addition, Scalar Multiplication and Product of Matrices
	7.2.5.	Operation of Transpose of a Matrix and its Properties
	7.2.6.	Symmetric and Skew-symmetric Matrices
	7.3.	Determinants
	7.3.1.	Determinants of Matrices of different order
	7.3.2.	Properties of Determinants (without proof)
	7.3.3.	Application of Factor Theorem to Determinants.
	7.3.4.	
	7.3.5.	Relation between a Determinant and its Cofactor Determinant
	7.3.6.	
	7.3.7.	Singular and non Singular matrix
O. M. State Almakera I	0 1	Introduction
8. Vector Algebra-l	8.1.	Introduction
8. Vector Algebra-I	8.2.	Scalars and Vectors
8. Vector Algebra-I		Scalars and Vectors Representation of a vector and types of vectors
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8. Vector Algebra-I	8.2. 8.3. 8.4.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6. 8.6.1.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors Resolution of a vector in two dimension Resolution of a vector in three
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6. 8.6.1.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors Resolution of a vector in two dimension Resolution of a vector in three dimension
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6. 8.6.1. 8.6.2.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors Resolution of a vector in two dimension Resolution of a vector in three dimension Matrix representation of a vector
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6. 8.6.1. 8.6.2.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors Resolution of a vector in two dimension Resolution of a vector in three dimension Matrix representation of a vector Direction Cosines and Direction Ratios Product of Vectors Angle between two vectors
8. Vector Algebra-I	8.2. 8.3. 8.4. 8.4.1. 8.4.2. 8.4.3. 8.4.4. 8.5. 8.6. 8.6.1. 8.6.2. 8.6.3. 8.7. 8.8.	Scalars and Vectors Representation of a vector and types of vectors Algebra of Vectors Addition of Vectors Difference between two Vectors Scalar multiplication of a vector Some properties and results Position vectors Resolution of Vectors Resolution of a vector in two dimension Resolution of a vector in three dimension Matrix representation of a vector Direction Cosines and Direction Ratios Product of Vectors

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	8.8.3.	Properties of Scalar Product (without proof)
	8.8.4.	Vector Product
	8.8.5.	Properties of vector product (without proof)
9. Differential Calculus- Limits and Continuity	9.1.	Introduction (Theorem 9.4 and Results 9.1-9.4 without proof)
	9.2.	Limits
	9.2.1.	The calculation of limits
	9.2.2.	One sided limits
	9.2.3.	Theorems on limits
	9.2.4.	Infinite limits and limits at infinity
	9.2.5.	Limits at infinity
	9.2.6.	Limits of rational functions
	9.2.7.	Applications of limits
	9.2.8.	Sandwich Theorem
	9.2.9.	Two special Trigonometrical limits
		Some important other limits
	9.3.	Continuity
	9.3.1.	Examples of functions Continuous at a point
	9.3.2.	Algebra of continuous functions
	9.3.3.	Removable and Jump Discontinuities
10. Differential Calculus-	10.1.	Introduction (Theorem 10.1-10.6 without proof)
Differentiability and Methods of	10.2.	The concept of derivative
Differentiation	10.2.1.	The tangent line problem
	10.2.2.	Velocity of Rectilinear motion
	THE RESIDENCE OF THE PARTY OF T	The derivative of a Function
State of the Late of Section 1.	10.2.4.	One sided derivatives (left hand and right hand derivatives)
A THE RESIDENCE OF THE PARTY OF	10.3.	Differentiability and Continuity
	10.4.	Differentiation Rules
		Derivatives of basic elementary functions
	The second of the second	Examples on Chain Rule
	10.4.3.	Implicit Differentiation

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	10.4.4. Logarithmic Differentiation
CHARLE MARKET	10.4.5. Substitution method
	10.4.6. Derivatives of variables defined by parametric equations
	10.4.7. Differentiation of one function with respect to another function :
	10.4.8. Higher order Derivatives
11. Integral Calculus	11.1. Introduction
	11.2. Newton-Leibnitz Integral
	11.3. Basic Rules of Integration
	11.4. Integrals of the Form ∫f(ax+b)dx
	11.5. Properties of Integrals (without proof)
	11.6. Simple applications
	11.7. Methods of Integration
	11.7.1. Decomposition method
	11.7.2. Decomposition by Partial Fractions
	11.7.3. Method of substitution of change of variable
	11.7.4. Important Results
	11.7.5. Integration by parts
	11.7.6. Bernoulli's formula for Integration by Parts
	11.7.8. Integrals of the form (i) $\int e^{a\chi} \sin b\chi d\chi$ (ii) $\int e^{a\chi} \cos b\chi d\chi$
	11.7.9. Integration of Rational Algebraic Functions
12. Introduction to	12.1. Introduction
probability Theory	12.2. Basic definitions
	12.3. Finite sample space (Theorem 12.3-12.6,12.8,12.10,12.11 without proof)
	12.4. Probability
	12.4.3. ODDS
	12.5. Some basic Theorems on Probability
	12.6. Conditional Probability
	12.6.1. Independent Events
	12.7. Total Probability of an event
	12.8. Bayes' Theorem